

Recap on eigenvalues and eigenvectors:

- $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ (or $T: V \rightarrow V$)

$v \in \mathbb{R}^n$ is an eigenvector of T if $v \neq 0$ and $T(v) = \lambda v$ for some $\lambda \in \mathbb{R}$.

eigenvalue

- To find eigenvalues, solve the characteristic equation $\det(T - \lambda \text{Id}) = 0$. Then, to find corresponding eigenvectors, find a basis of $E_\lambda = \ker(T - \lambda \text{Id})$.

λ -eigenspace

Ex: $T = \begin{pmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{pmatrix}$

$T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

For example, expand here to compute determinant

$$T - \lambda \text{Id} = \begin{pmatrix} 1-\lambda & 3 & 3 \\ -3 & -5-\lambda & -3 \\ 3 & 3 & 1-\lambda \end{pmatrix}$$

$$\begin{aligned} 0 = \det(T - \lambda \text{Id}) &= (1-\lambda) \det \begin{pmatrix} -5-\lambda & -3 \\ 3 & 1-\lambda \end{pmatrix} \\ &\quad - 3 \det \begin{pmatrix} -3 & -3 \\ 3 & 1-\lambda \end{pmatrix} \\ &\quad + 3 \det \begin{pmatrix} -3 & -5-\lambda \\ 3 & 3 \end{pmatrix} \end{aligned}$$

$$\begin{aligned}
&= (1-\lambda) \left[(-5-\lambda)(1-\lambda) + 9 \right] \\
&\quad - 3 \left[-3(1-\lambda) + 9 \right] + 3 \left[-9 + (5+\lambda) \cdot 3 \right] \\
&= (1-\lambda) (-5 + 5\lambda - \lambda + \lambda^2 + 9) \\
&\quad - 3(3\lambda + 6) + 3(3\lambda + 6) \\
&= (1-\lambda)(\lambda^2 + 4\lambda + 4) \\
&= (1-\lambda)(\lambda + 2)^2.
\end{aligned}$$

Characteristic equation: $(\lambda + 2)^2(\lambda - 1) = 0$

double root
of the equation

Solutions are $\begin{cases} \lambda_2 = -2 & \text{algebraic multiplicity } 2 \\ \lambda_1 = 1 & \text{algebraic multiplicity } 1 \end{cases}$

Look for bases of $E_{-2} = \text{Ker}(T + 2\text{Id})$, $E_1 = \text{Ker}(T - \text{Id})$.

E_{-2} : $T + 2\text{Id} = \begin{pmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{pmatrix} + 2\text{Id} = \begin{pmatrix} 3 & 3 & 3 \\ -3 & -3 & -3 \\ 3 & 3 & 3 \end{pmatrix}$

R.R. $\sim \begin{pmatrix} 4 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \rightsquigarrow \begin{cases} x_1 = -x_2 - x_3 \\ x_2 \text{ free} \\ x_3 \text{ free} \end{cases}$

$\left. \begin{matrix} x_2 = 1 \\ x_3 = 0 \end{matrix} \right\} \Rightarrow x_1 = -1 \quad \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \quad \left. \begin{matrix} x_2 = 0 \\ x_3 = 1 \end{matrix} \right\} \Rightarrow x_1 = -1 \quad \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$

$$E_{-2} = \text{span} \left\{ \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \right\}$$

basis for this eigenspace.

$$\underline{E_1}: T - \text{Id} = \begin{pmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{pmatrix} - \text{Id} = \begin{pmatrix} 0 & 3 & 3 \\ -3 & -6 & -3 \\ 3 & 3 & 0 \end{pmatrix} \sim$$

$$\text{R.R.} \sim \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} \rightsquigarrow \begin{cases} x_1 = -x_2 \\ x_2 = -x_3 \\ x_3 \text{ free} \end{cases} \quad x_3 = 1 \quad \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

$$E_1 = \text{span} \left\{ \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \right\}$$

basis for this eigenspace.

Diagonalizing a matrix / linear transformation

$$T = \begin{pmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{pmatrix} \xrightarrow{\text{diagonalize}} D = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{pmatrix}$$

original / input

diagonal / output

unique up to reordering the diagonal entries

Def: The matrix / linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is diagonalizable if there exists an isomorphism $P: \mathbb{R}^n \rightarrow \mathbb{R}^n$ such that $T = P D P^{-1}$ where D is diagonal.

invertible linear trans

$$\underline{\text{Note:}} \quad \boxed{T = P D P^{-1}} \Leftrightarrow P^{-1} T P = \underbrace{P^{-1} P}_{= \text{Id}} D \underbrace{P P^{-1}}_{= \text{Id}} = D$$

$$\text{"conjugation by } P \text{"} \Leftrightarrow \boxed{P^{-1} T P = D}$$

From previous video:

$$\left. \begin{array}{l} \text{basis for } E_1: \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \\ \text{basis for } E_{-2}: \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \end{array} \right\} \Rightarrow P = \begin{pmatrix} 1 & -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

"change of basis"

Check that:

$$\underbrace{D = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{pmatrix}}_{\text{output}} = P^{-1} \underbrace{\begin{pmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{pmatrix}}_{\text{input}} P$$

Some matrices are not diagonalizable:

$$T = \begin{pmatrix} 2 & 4 & 3 \\ -4 & -6 & -3 \\ 3 & 3 & 1 \end{pmatrix} \quad \det(T - \lambda \text{Id}) = \underbrace{(1 - \lambda)(\lambda + 2)^2}$$

← same as in the previous example!

$$\lambda_1 = 1 \quad \text{w/ multiplicity } 1$$

$$\lambda_2 = -2 \quad \text{w/ multiplicity } 2$$

Now, find bases for E_1 and E_{-2} .

$$\begin{aligned} \underline{E_1}: \quad T - \text{Id} &= \begin{pmatrix} 2 & 4 & 3 \\ -4 & -6 & -3 \\ 3 & 3 & 1 \end{pmatrix} - \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \\ &= \begin{pmatrix} 1 & 4 & 3 \\ -4 & -7 & -3 \\ 3 & 3 & 0 \end{pmatrix} \xrightarrow{\text{R.R.}} \begin{pmatrix} 1 & 4 & 3 \\ 1 & 1 & 0 \\ 0 & -3 & -3 \end{pmatrix} \xrightarrow{\text{R.R.}} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} \end{aligned}$$

$$\leadsto \begin{cases} x_1 = -x_2 \\ x_2 = -x_3 \\ x_3 \text{ free} \end{cases} \quad \text{Choose } x_3 = 1:$$

$$E_1 = \text{span} \left\{ \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \right\}$$

$$\underline{E_{-2}}: \begin{pmatrix} 2 & 4 & 3 \\ -4 & -6 & -3 \\ 3 & 3 & 1 \end{pmatrix} + 2 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 4 & 4 & 3 \\ -4 & -4 & -3 \\ 3 & 3 & 3 \end{pmatrix} \sim \text{R.R.}$$

$$\sim \begin{pmatrix} 1 & 1 & 3/4 \\ 0 & 0 & 0 \\ 1 & 1 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 3/4 \\ 0 & 0 & 0 \\ 0 & 0 & 1/4 \end{pmatrix}$$

How many free variables?

just 1: x_2 free

$$\leadsto \begin{cases} x_1 = -x_2 - \frac{3}{4}x_3 = -x_2 \\ x_2 \text{ free} \\ x_3 = 0 \end{cases}$$

Choose $x_2 = 1$:

$$E_{-2} = \text{span} \left\{ \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \right\}$$

Putting all eigenvectors together; $\begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$.

No third one!

This T is not diagonalizable!

The issue is that

$$\dim E_{-2} = 1 < 2 = \text{mult}(-2)$$

(even though: $\dim E_1 = 1 = \text{mult}(1)$)

Theorem. An $n \times n$ matrix whose distinct real eigenvalues are $\lambda_1, \lambda_2, \dots, \lambda_p$ is diagonalizable if and only

if $\dim E_{\lambda_j} = \text{mult}(\lambda_j)$ and $\sum_{j=1}^p \text{mult}(\lambda_j) = n$.

dimension of
the λ_j -eigenspace
"geometric multiplicity"

number of
times that λ_j
appears as a
root of characteristic
equation
"algebraic multiplicity"

the characteristic
equation factors
completely as
 $(\lambda - \lambda_1)^{m_1} (\lambda - \lambda_2)^{m_2} \dots (\lambda - \lambda_p)^{m_p}$
 $1 \leq m_j = \text{mult}(\lambda_j)$
w/ $\lambda_j \in \mathbb{R}$.

In general, $\dim E_{\lambda_j} \leq \text{mult}(\lambda_j)$.

• Ways in which matrices can fail to be diagonalizable:

Ex 1: $A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$

Characteristic equation:
 $\det(A - \lambda I) = -\lambda^3 = 0$
has solution $\lambda_1 = 0$.

$E_0 = \text{Ker } A = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\}$

$\begin{cases} x_2 = 0 \\ x_3 = 0 \\ x_1 \text{ free} \end{cases} \xrightarrow{x_1=1} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$

$\dim E_0 = 1 < 3 = \text{mult}(0)$

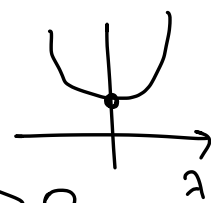
$B = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \quad B: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

Characteristic equation:
 $\det(B - \lambda I) = \lambda^2 + 1 > 0$

has no real roots!

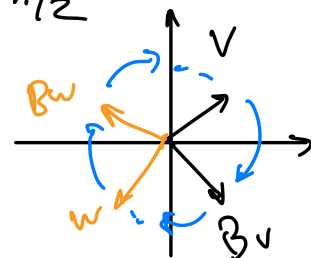
$\sum_{j=1}^p \text{mult}(\lambda_j) = 0 < 2 = n$

Side note:
 $\lambda = \pm i$
are complex
eigenvalues



Geometric explanation:

$B = R_\theta$ for $\theta = \pi/2$
rotation by $\pi/2$



- A way to guarantee that a matrix is diagonalizable:
"sufficient condition"

Prop: If A is an $n \times n$ matrix and it has n distinct eigenvalues, then A is diagonalizable.

Pf: If A has n distinct eigenvalues, then the char. eqn. factors as $\det(A - \lambda \text{Id}) = (\lambda - \lambda_1)(\lambda - \lambda_2) \dots (\lambda - \lambda_n)$
polynomial of degree n $\uparrow$ n distinct roots

Therefore $\text{mult}(\lambda_j) = 1$; so $\sum_{j=1}^n \text{mult}(\lambda_j) = n$.

$1 \leq \dim E_{\lambda_j} \leq \text{mult}(\lambda_j) = 1$, so $\dim E_{\lambda_j} = \text{mult}(\lambda_j)$;

Thus A is diagonalizable by Theorem above. $\square$

Ex:

$$A = \begin{pmatrix} 1 & 0 & 3 & 41 & e & 1 \\ 0 & 2 & 4 & \pi & 1/2 & 1 \\ 0 & 0 & -1 & 5 & 15 & 0 \\ 0 & 0 & 0 & -7 & 8 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 4 \end{pmatrix}$$

6×6 matrix

Q: Is A diagonalizable?

A: Yes! The matrix A is diagonalizable because its eigenvalues are

$1, 2, -1, -7, 0, 4$, which are 6 distinct eigenvalues.

Note: $\det(A - \lambda \text{Id}) = (1 - \lambda)(2 - \lambda)(-1 - \lambda)(-7 - \lambda)(-\lambda)(4 - \lambda)$
all distinct roots!

Why would we want to diagonalize a matrix?

Reason 1: "Geometrically recognize" how a linear transformation acts on the space

Reason 2: Singular Value Decomposition, Principal Component Analysis
Machine learning, models of Markov chains, etc.

↑
to be
discussed
more in
a future class!

if the matrix is
diagonalizable.

Reason 3: To facilitate computation of powers of matrices.

$$A = \begin{pmatrix} 4 & -3 \\ 2 & -1 \end{pmatrix}$$

$$A^8 = ?$$

$$A^{2022} = ?$$

$$A^2 = \begin{pmatrix} 4 & -3 \\ 2 & -1 \end{pmatrix} \begin{pmatrix} 4 & -3 \\ 2 & -1 \end{pmatrix} = \begin{pmatrix} 10 & -9 \\ 6 & -5 \end{pmatrix}$$

$$A^3 = \underbrace{\begin{pmatrix} 10 & -9 \\ 6 & -5 \end{pmatrix}}_{A^2} \begin{pmatrix} 4 & -3 \\ 2 & -1 \end{pmatrix} = \begin{pmatrix} 22 & -21 \\ 14 & -13 \end{pmatrix}$$

∴ there's a better way!

$$D = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$$

$$D^2 = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} = \begin{pmatrix} \lambda_1^2 & 0 \\ 0 & \lambda_2^2 \end{pmatrix}$$

$$D^n = \begin{pmatrix} \lambda_1^n & 0 \\ 0 & \lambda_2^n \end{pmatrix}$$

Diagonalizing A we have $A = PDP^{-1}$

$$A^8 = \underbrace{(PDP^{-1})}_A \underbrace{(PDP^{-1})}_A \cdots \underbrace{(PDP^{-1})}_A = PD^8P^{-1}$$

all P 's and (P^{-1}) 's cancel

So let's diagonalize $A = \begin{pmatrix} 4 & -3 \\ 2 & -1 \end{pmatrix}!$

Characteristic equation:

$$\det(A - \lambda \text{Id}) = \det \begin{pmatrix} 4-\lambda & -3 \\ 2 & -1-\lambda \end{pmatrix} = (4-\lambda)(-1-\lambda) + 6$$

$$= -4 - 4\lambda + \lambda + \lambda^2 + 6 = \lambda^2 - 3\lambda + 2 = (\lambda - 2)(\lambda - 1)$$

Eigenvalues are 2 and 1, both have multiplicity 1.

Find bases for the eigenspaces:

$$E_2 = \ker(A - 2\text{Id}) = \text{span} \left\{ \begin{pmatrix} 3 \\ 2 \end{pmatrix} \right\}$$

$$A - 2\text{Id} = \begin{pmatrix} 2 & -3 \\ 2 & -3 \end{pmatrix} \sim \begin{pmatrix} 1 & -3/2 \\ 0 & 0 \end{pmatrix} \rightsquigarrow \begin{cases} x_1 = 3/2 x_2 \\ x_2 \text{ free} \end{cases} \quad \begin{array}{l} \text{choose } x_2 = 2 \\ v_1 = \begin{pmatrix} 3 \\ 2 \end{pmatrix} \end{array}$$

$$E_1 = \ker(A - \text{Id}) = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$$

$$A - \text{Id} = \begin{pmatrix} 3 & -3 \\ 2 & -2 \end{pmatrix} \sim \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix} \rightsquigarrow \begin{cases} x_1 = x_2 \\ x_2 \text{ free} \end{cases} \quad \begin{array}{l} \text{choose } x_2 = 1 \\ v_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \end{array}$$

$$P = \begin{pmatrix} | & | \\ v_1 & v_2 \\ | & | \end{pmatrix} = \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix} \quad \text{is such that } A = P D P^{-1}$$

$$\text{where } D = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}.$$

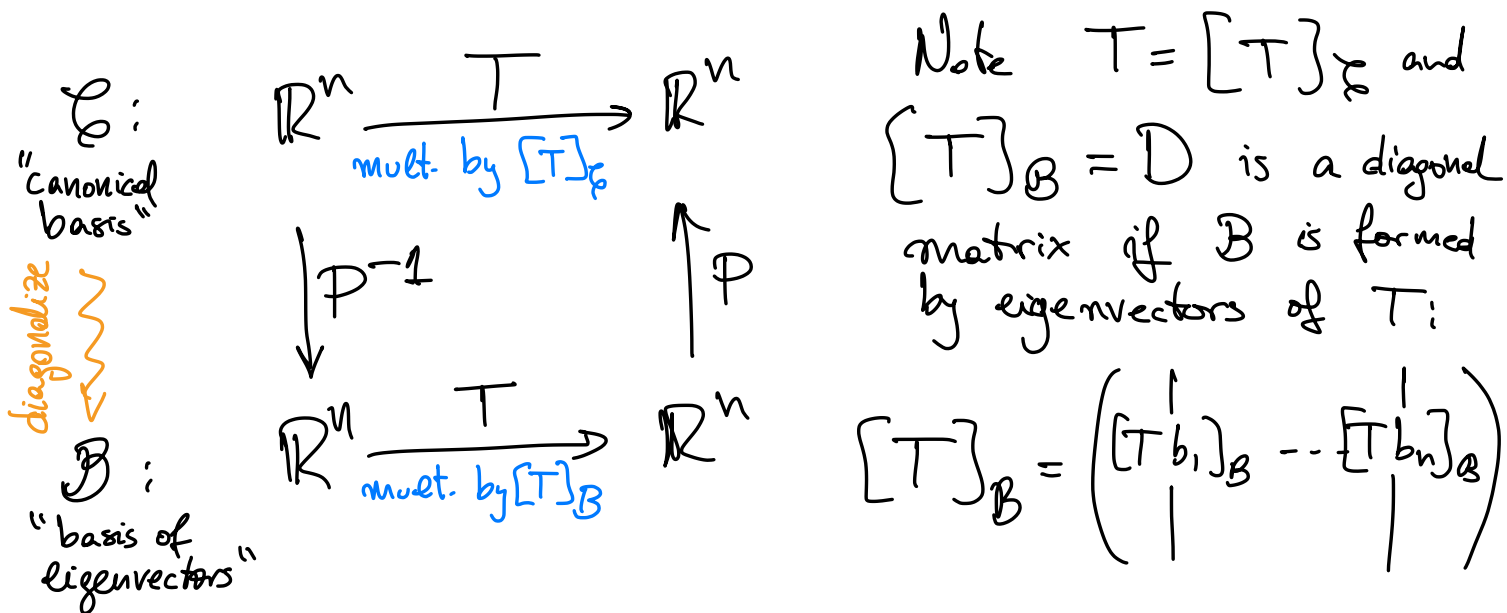
$$(P \mid Id) \xrightarrow{R.R.} \dots \sim (Id \mid \boxed{P^{-1}}) \quad \text{find inverse} \quad P^{-1} = \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix}$$

$$A^8 = P D^8 P^{-1} = \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 2^8 & 0 \\ 0 & 1^8 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix}$$

$= \begin{pmatrix} 766 & -765 \\ 510 & -509 \end{pmatrix}$

$$A^{2022} = P D^{2022} P^{-1} = \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 2^{2022} & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix}$$

Capstone: Relating diagonalization w/ change of basis



Indeed, if $B = \{b_1, \dots, b_n\}$ is formed by eigenvectors, then

$$Tb_1 = \lambda_1 b_1, \quad Tb_2 = \lambda_2 b_2, \quad \dots, \quad Tb_n = \lambda_n b_n$$

$$[Tb_1]_B = \begin{pmatrix} \lambda_1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \quad [Tb_2]_B = \begin{pmatrix} 0 \\ \lambda_2 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$[T]_B = \begin{pmatrix} \lambda_1 & 0 & & 0 \\ 0 & \lambda_2 & & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & & \lambda_n \end{pmatrix} = D \text{ is diagonal!}$$

w.r.t. canonical basis $\mathcal{E}$

$$\mathbb{R}^n \xrightarrow[\text{mult. by } [T]_{\mathcal{E}}]{T} \mathbb{R}^n$$

$$\downarrow P^{-1}$$

$$\mathbb{R}^n \xrightarrow[\text{mult. by } [T]_B]{T} \mathbb{R}^n$$

with respect to basis B
of eigenvectors

$$P = P_{\mathcal{E} \leftarrow B} = \begin{pmatrix} | & & | \\ [b_1]_{\mathcal{E}} & \dots & [b_n]_{\mathcal{E}} \\ | & & | \end{pmatrix}$$

$$P^{-1} = P_{B \leftarrow \mathcal{E}}$$

Change of basis
matrix from B to $\mathcal{E}$

exists iff $[T]_{\mathcal{E}}$ is
diagonalizable

$$[T]_{\mathcal{E}} = P_{\mathcal{E} \leftarrow B} [T]_B P_{B \leftarrow \mathcal{E}}$$

$$A = P D P^{-1}$$